# Hydrodynamics and Magnetohydrodynamics: Solutions of the exercises in Lecture XI 

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## Lecture XI, Exercise 1.

The Rankine-Hugoniot conditions are express the conservation of rest mass, energy and momentum across a shock wave

$$
\begin{align*}
& \llbracket \rho u^{\mu} \rrbracket n_{\mu}=0,  \tag{1}\\
& \llbracket T^{\mu \nu} \rrbracket n_{\nu}=0 . \tag{2}
\end{align*}
$$

For simplicity, we assume the flow is one-dimensional and the space-time is flat, then $n_{\mu}=(0,1,0,0)$. Evaluating the equations (1) and (2) in the shock-front rest frame, they are written as

$$
\begin{equation*}
\rho_{a} v_{a}^{x}=\rho_{b} v_{b}^{x}, \quad T_{a}^{x x}=T_{b}^{x x}, \quad T_{a}^{t x}=T_{b}^{t x} \tag{3}
\end{equation*}
$$

or equivalently,

$$
\begin{align*}
J:=\rho_{a} W_{a} v_{a} & =\rho_{b} W_{b} v_{b},  \tag{4}\\
\rho_{a} h_{a} W_{a}^{2} v_{a}^{2}+p_{a} & =\rho_{b} h_{b} W_{b}^{2} v_{b}^{2}+p_{b},  \tag{5}\\
\rho_{a} h_{a} W_{a}^{2} v_{a} & =\rho_{b} h_{b} W_{b}^{2} v_{b}, \tag{6}
\end{align*}
$$

where $J$ is referred to the relativistic mass flux. From equations (4) and (5), the condition of the relativistic mass flux across the shock front is given by

$$
\begin{equation*}
\llbracket J^{2} \rrbracket=0, \quad J^{2}=-\frac{\llbracket p \rrbracket}{\llbracket h / \rho \rrbracket} . \tag{7}
\end{equation*}
$$

Similarly, using equations (4) and (6) we can rewrite the conservation of momentum as

$$
\begin{equation*}
\llbracket h W \rrbracket=0 . \tag{8}
\end{equation*}
$$

Multiplying eq (7) by ( $h_{a} / \rho_{a}+h_{b} / \rho_{b}$ ) and combining it with eq (4) we obtain

$$
\begin{equation*}
\left(h_{a} W_{a} v_{a}\right)^{2}-\left(h_{b} W_{b} v_{b}\right)^{2}=-\left(\frac{h_{a}}{\rho_{a}}+\frac{h_{b}}{\rho_{b}}\right) \llbracket p \rrbracket . \tag{9}
\end{equation*}
$$

We then take the square of eq (8) and subtract it from eq (9) to obtain

$$
\begin{equation*}
\llbracket h^{2} \rrbracket=\left(\frac{h_{a}}{\rho_{a}}+\frac{h_{b}}{\rho_{b}}\right) \llbracket p \rrbracket . \tag{10}
\end{equation*}
$$

This is called Taub adiabat which represents the relativistic generalization of the classical Hugoniot adiabat for Newtonian shock fronts.

Next we consider the Newtonian limit of the Taub adiabat. In the Newtonian limit $h=1+\epsilon+p / \rho \approx 1$ and that $\llbracket h^{2} \rrbracket \approx 2 \llbracket \epsilon+p / \rho \rrbracket$. Therefore from eq (10), the Newtonian limit of the Taub adiabat is given by

$$
\begin{equation*}
\llbracket \epsilon+\frac{p}{\rho} \rrbracket=\frac{1}{2}\left(\frac{1}{\rho_{a}}+\frac{1}{\rho_{b}}\right) \llbracket p \rrbracket . \tag{11}
\end{equation*}
$$

This is equivalent with the classical Hugoniot adiabat for Newtonian shock fronts.

## Lecture XI, Exercise 2.

The junction conditions can be expressed in terms of the velocities on the each side of the shock front in terms of the physical states there, i.e.,

$$
\begin{equation*}
v_{a}^{2}=\frac{\left(p_{a}-p_{b}\right)\left(e_{b}+p_{a}\right)}{\left(e_{a}-e_{b}\right)\left(e_{a}+p_{b}\right)} . \tag{12}
\end{equation*}
$$

Here we assume a highly relativistic shock, a cold fluid ahead of the shock, and an ultra relativistic one behind the shock, i.e.,

$$
\begin{equation*}
W_{a} \gg 1, \quad p_{a} \approx 0, \quad e_{a} \approx \rho_{a}, \quad p_{b}=\frac{e_{b}}{3} . \tag{13}
\end{equation*}
$$

Then the eq (12) can be written as

$$
\begin{equation*}
v_{a}^{2}=\frac{-e_{b} \cdot e_{b} / 3}{\left(e_{a}-e_{b}\right)\left(e_{a}+e_{b} / 3\right)} . \tag{14}
\end{equation*}
$$

The denominator of eq (14) can be expanded as

$$
\begin{align*}
\frac{1}{3}\left(e_{a}-e_{b}\right)\left(3 e_{a}+e_{b}\right) & =\frac{1}{3}\left(3 e_{a}^{2}+e_{a} e_{b}-3 e_{a} e_{b}-e_{b}^{2}\right)  \tag{15}\\
& \simeq \frac{1}{3}\left(-2 e_{a} e_{b}-e_{b}^{2}\right)  \tag{16}\\
& =-\frac{e_{b}^{2}}{3}\left(2 \frac{e_{a}}{e_{b}}+1\right) . \tag{17}
\end{align*}
$$

where we have used $e_{a}^{2} \ll e_{b}^{2}, e_{a}^{2} \ll e_{a} e_{b}$. Using eq (17), eq (14) can be expressed as

$$
\begin{equation*}
v_{a}^{2} \simeq \frac{-e_{b}^{2} / 3}{-e_{b}^{2} / 3\left(2 e_{a} / e_{b}+1\right)}=\frac{1}{2 e_{a} / e_{b}+1} . \tag{18}
\end{equation*}
$$

This equation can be rewritten as

$$
\begin{align*}
\left(2 e_{a} / e_{b}+1\right) v_{a}^{2} & =1 \\
2 e_{a} v_{a}^{2}+e_{b} v_{a}^{2} & =e_{b} \\
e_{b}\left(1-v_{a}^{2}\right) & =2 e_{a} v_{a}^{2} \\
e_{b} W_{a}^{-2} & =2 e_{a} v_{a}^{2} \\
e_{b} & =2 e_{a} v_{a}^{2} W_{a}^{2} \\
& =2 e_{a}\left(W_{a}^{2}-1\right) \\
& \simeq 2 e_{a} W_{a}^{2} \tag{19}
\end{align*}
$$

where we have used that $W_{a}^{2} \gg 1$. In this case, the shock is ultra-relativistic relative to the fluid ahead and because the latter is cold, the shock front is also ultra-relativistic in the Eulerian frame, i.e.,

$$
\begin{equation*}
W_{a}^{2} \sim W_{s}^{2} \gg 1 \rightarrow e_{b}=2 e_{a} W_{a}^{2} \sim e_{a} W_{s}^{2} \tag{20}
\end{equation*}
$$

